

## Abstract

This document will demonstrate how to use nRF24L01+ RF module with Arduino™.

## Introduction

Nowadays, wireless is widely adopted in different areas or fields such as mobile communications (e.g. WIFI, Mobile Phone), control system, remote car and helicopter. This document is going to demonstrate how a MCU controls a RF module for wireless communication.

In this library, the nRF24L01+ is able to work in Shock Burst Mode with max. 32 Bytes Payload, (Payload means Data), or Dynamic Payload Length Mode. There three well commented sample codes are integrated with Library. Please study the sample codes and refer to the datasheet if need.

This document is only showed how to use this library as an interface to control nRF24L01+ RF Module. The operations in details will be discussed here. If you concern or are interested in the operations of nRF24L01+, please refer to the datasheet.

## Specifications

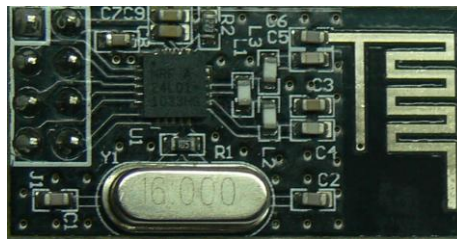
VCC/VDD <sup>1</sup>	1.9V — 3.6V
RF	2.4GHz
Channel	125
Shock Burst Mode	Yes
Dynamic Payload Length Mode	Yes
Receiver Data Pipe	6
Built-in Auto Acknowledgement	Yes
Communication Interface	SPI

1. If input Signal > 3.6V, the VDD must be from 2.7V to 3.3V.

## Pin Outs

Pin outs:

1 GND	2 VDD
3 CE	4 CSN
5 SCK	6 MOSI
7 MISO	8 IRQ



Left Upper Corner is 1.

## Install nRF24L01+ Library

Install the nRF24L01+ library

- copy nRF24L01P folder to <Arduino Folder>\libraries

Note: If the Arduino software is running when copying library. The Arduino is needed to be restarted after copying the files.

After successful installation of nRF24L01+ library, there are some examples can be found from the menu File -> Examples -> nRF24L01P, as shown in Fig. 1.

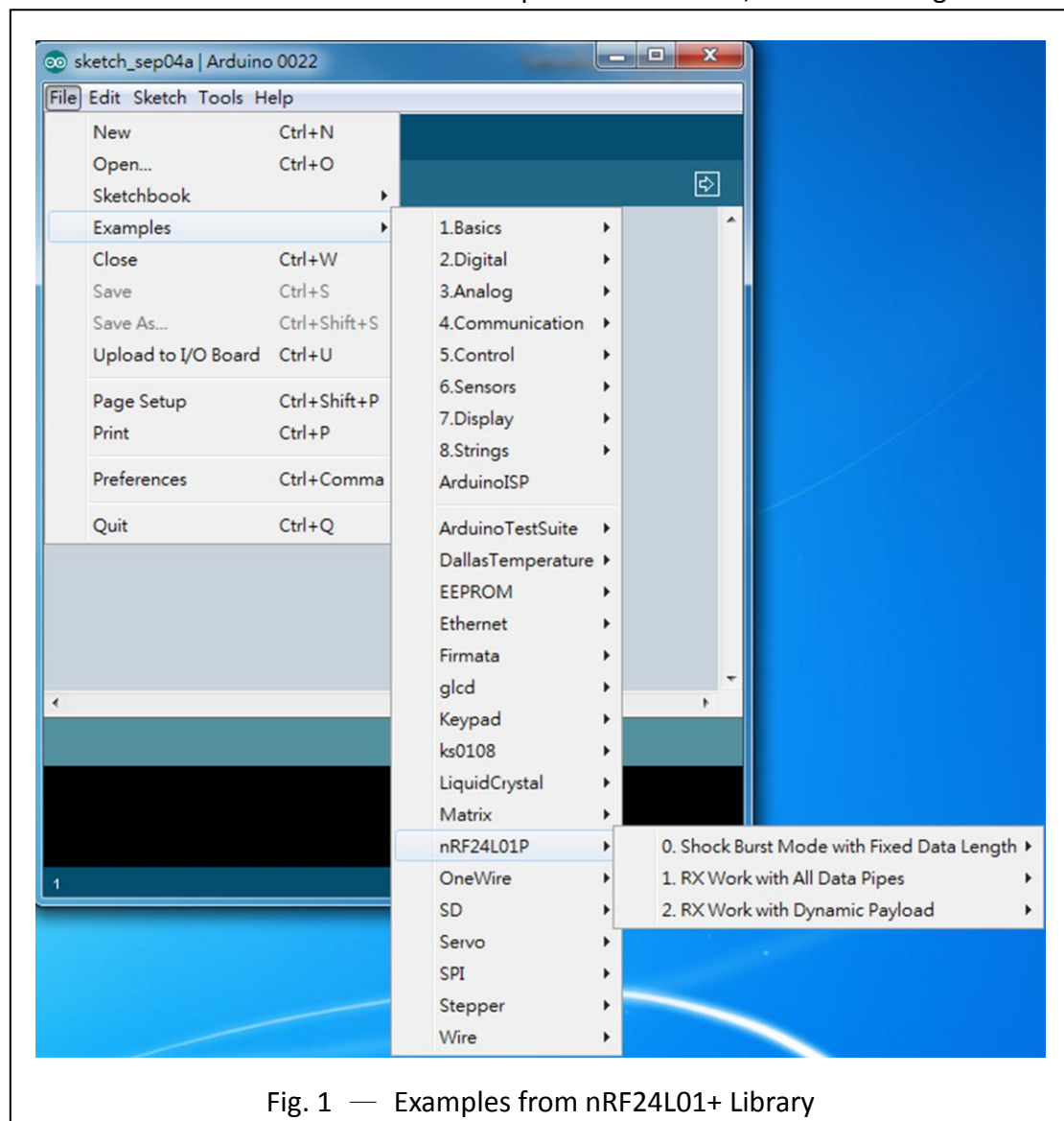
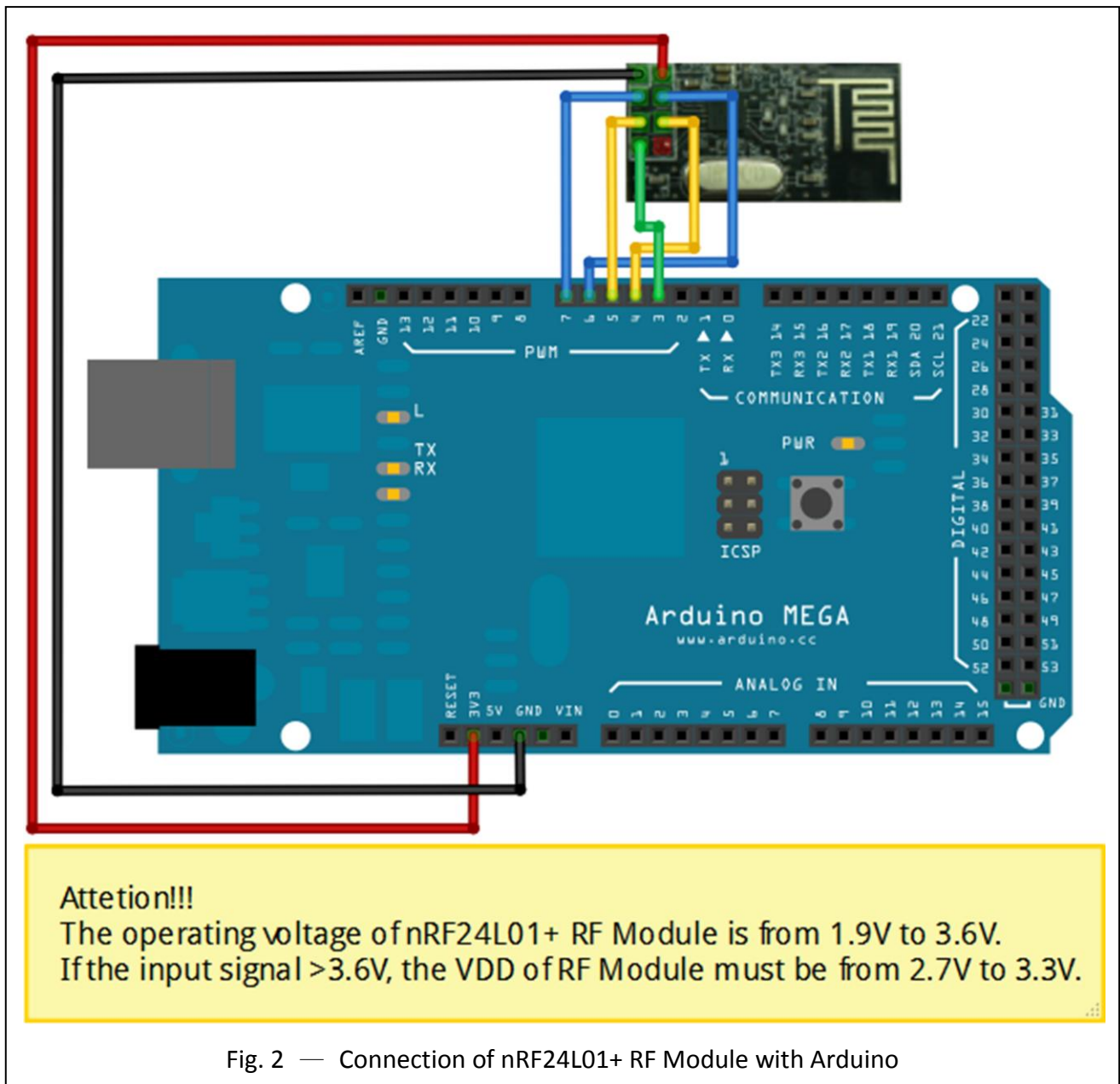


Fig. 1 — Examples from nRF24L01+ Library

## Set nRF24L01+ as a Transmitter



1. Connect the nRF24L01+ RF Module with Arduino as shown in Fig. 2.
2. Upload TX (Transmitter) Example Codes to Arduino, menu File -> Examples  
 -> nRF24L01P -> 0. Shock Burst Mode with Fixed Data Length -> TX

## Set nRF24L01+ as a Receiver

1. Connect the nRF24L01+ RF Module with another Arduino, shown in Fig. 2.
2. Upload TX (Transmitter) Example Codes to Arduino, menu File -> Examples  
 -> nRF24L01P -> 0. Shock Burst Mode with Fixed Data Length -> RX

3. Click menu Tools -> Serial Monitor and Set the baud rate to be 115200

If all settings are correct, the Serial Monitor of Arduino Board with a nRF24L01+ RF Module working as a Receiver will display some data, as shown in Fig. 3.

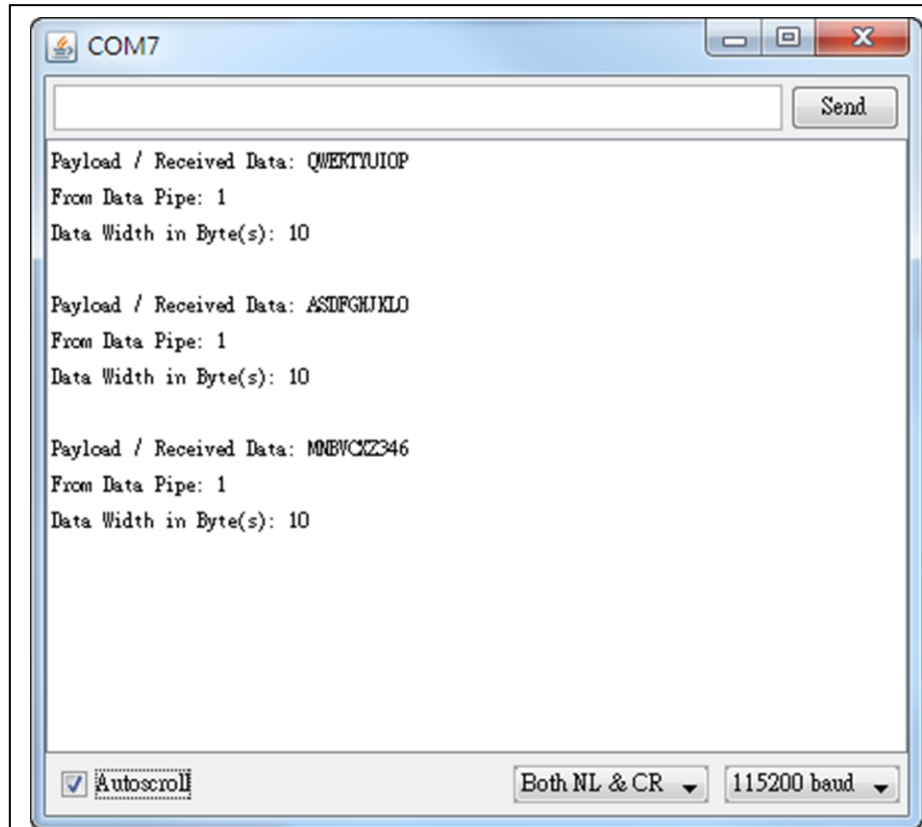


Fig. 3 — Data Received and Display with Serial Monitor

## Setting of nRF24L01+

Some parameters or setting should be set before any wireless communication operations.

- Set nRF24L01+ working mode, Shock Burst Mode or Dynamic Payload Mode
- Set the width of address, 3 Bytes to 5 Bytes
- Set the address for Transmitter and Receiver  
Note: Receiver Address of Data Pipe 0 must be same as Transmitter's Address for activating Auto Acknowledgment Function.
- Set operating channel which is from 0 to 125
- Set the Payload width. The payload width of Transmitter and Receiver must be same, otherwise there is malfunction.

## Library of nRF24L01+

Function : nRF24L01P(int cePin, int csnPin, int clkPin, int mosiPin, int misoPin)

Parameters : cePin — CE Pin of nRF24L01+ is connected to Arduino Board.

csnPin — CSN Pin of nRF24L01+ is connected to Arduino Board.

clkPin — CLK Pin of nRF24L01+ is connected to Arduino Board.

mosiPin — MOSI Pin of nRF24L01+ is connected to Arduino Board.

misoPin — MISO Pin of nRF24L01+ is connected to Arduino Board.

Description : Constructor of nRF24L01P Class

Set up the connection pins of nRF24L01+ RF module

Return : none

Notes : none

Function : void DefaultShockBurstSetting(void)

Parameters : none

Description : Set nRF24L01+ RF Module works in

Shock Burst Mode,

Switch to Receiver Mode,

Enable Receiver Address Data Pipe 0 and 1

Set RX and TX Address Width 5 Bytes

Set Retransmission Delay 4 ms

Set Retransmission Count 15

Set Operating Channel 23

Set Speed Air Rate 2Mbps

Set RF Power 0dBm

Flush TX and RX Buffer

Clear Status Register

Return : none

Notes : none

Function : void DefaultDynamicPayloadSetting(void)

Parameters : none

Description : Initial Setting as same as Default Shock Burst Setting and Enable Data Pipe 0 and 1 operates in Dynamic Payload Mode.

Return : none

Notes : none

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Function : void PowerUP(void)  
Parameters : none  
Description : Power Up nRF24L01+ Device  
Return : none  
Notes : none

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Function : void PowerDown (void)  
Parameters : none  
Description : Power Down nRF24L01+ Device  
Return : none  
Notes : none

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Function : void DisableRxDrInterrupt (void)  
Parameters : none  
Description : Disable nRF24L01+ Interrupt when data are received.  
Return : none  
Notes : none

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Function : void EnableRxDrInterrupt (void)  
Parameters : none  
Description : Enable nRF24L01+ Interrupt when data are received.  
Return : none  
Notes : none

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Function : void DisableTxDsInterrupt (void)  
Parameters : none  
Description : Disable nRF24L01+ Interrupt when data are transmitted successfully.  
Return : none  
Notes : none

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Function : void EnableTxDsInterrupt (void)  
Parameters : none  
Description : Enable nRF24L01+ Interrupt when data are transmitted successfully.  
Return : none  
Parameters : none  
Note : none

Function	:	void DisableMaxRtInterrupt(void
Description	:	Disable nRF24L01+ Interrupt when counts of data retransmitted are reaching to maximum counts.
Return	:	none
Notes	:	none

Function	: void EnableMaxRtlInterrupt (void)
Parameters	: none
Description	: Enable nRF24L01+ Interrupt when counts of data retransmitted are reaching to maximum counts.
Return	: none
Notes	: none

Function	: void DisableCRC (void)
Parameters	: none
Description	: Disable nRF24L01+'s internal CRC function
Return	: none
Notes	: none

Function	:	void EnableCRC(unsigned char scheme)
Parameters	:	scheme — 0 for 1 Byte CRC 1 for 2 Bytes CRC
Description	:	Enable nRF24L01+'s internal CRC function
Return	:	none
Notes	:	none

Function	: void EnableAutoAck(unsigned char pipe)
Parameters	: pipe — Auto Acknowledgement of Data Pipe to be enable Which is from 0 to 5
Description	: Enable Data Pipe 0 to 5 Auto Acknowledgement Function
Return	: none
Notes	: none



Function : void DisableAutoAck (unsigned char pipe)  
Parameters : pipe — Auto Acknowledgement of Data Pipe to be disable  
Which is from 0 to 5  
Description : Diable Data Pipe 0 to 5 Auto Acknowledgement Function  
Return : none  
Notes : none

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Function : void DisableAutoAck (unsigned char pipe)  
Parameters : pipe — Auto Acknowledgement of Data Pipe to be disable  
Which is from 0 to 5  
Description : Diable Data Pipe 0 to 5 Auto Acknowledgement Function  
Return : none  
Notes : none

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Function : void DisableDataPipe (unsigned char pipe)  
Parameters : pipe — Data Pipe to be disable, which is from 0 to 5  
Description : Diable Data Pipe 0 to 5  
Return : none  
Notes : none

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Function : void EnableDataPipe (unsigned char pipe)  
Parameters : pipe — Data Pipe to be enable, which is from 0 to 5  
Description : Enable Data Pipe 0 to 5  
Return : none  
Notes : none

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Function : void DisableRXAddr (unsigned char pipe)  
Parameters : pipe — Data Pipe to be disable, which is from 0 to 5  
Description : Diable Data Pipe 0 to 5  
Return : none  
Notes : note

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Function : void EnableRXAddr (unsigned char pipe)  
Parameters : pipe — Data Pipe to be enable, which is from 0 to 5  
Description : Enable Data Pipe 0 to 5  
Return : none  
Notes : none

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Function : void setAddressWidth(unsigned char AddrWidth)  
Parameters : AddrWidth — Set Address Width which is from 3 to 5 Bytes  
Description : Set Address Width  
Return : none  
Notes : Default is 5 Bytes

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Function : unsigned char getAddressWidth(void)  
Parameters : none  
Description : Get Address Width  
Return : Address Width, which is from 3 to 5 Bytes  
Notes : none

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Function : void setAutoRD(unsigned char AutoRD)  
Parameters : AutoRD — Auto Re-transmission Delay, which is from 0 to 15  
Description : Set Auto Re-transmission Delay  
Auto Re-transmission Delay:  $(\text{AutoRD} + 1) * 250\mu\text{s}$   
Return : none  
Notes : Please refer to data sheet for the details

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Function : void setAutoReCount(unsigned char AutoCount)  
Parameters : AutoCount — Auto Re-transmission Count, which is from 0 to 15  
Description : Set Auto Re-transmission Count  
Return : none  
Notes : Please refer to data sheet for the details  
If the Auto Retransmission Count is reached and the data is not transmitted out successfully, an interrupt will be occurred. This can be checked by MaxRt() function.

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Function : void setSpeedAirRate(unsigned char Speed)  
Parameters : Speed — 0 for 1Mbps, 1 for 2 Mbps, 2 for 250Kbps  
Or use  
SpeedAirRate\_1MBPS  
SpeedAirRate\_2MBPS  
SpeedAirRate\_250KBPS  
Description : Set Air Speed Data Rate  
Return : none  
Notes : none

Function : void setRFPower(unsigned char PWR)

Parameters : PWR — 0 for -18dBm  
                  1 for -12dBm  
                  2 for -6dBm  
                  3 for 0dBm

Description : Set RF Power

Return : none

Notes : none

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Function : void WriteRegByte(unsigned char reg, unsigned char value)

Parameters : reg — Register to be written  
                  value — Value to be written to register

Description : Write value to register

Return : none

Notes : Refer to Datasheet for details of registers and parameters

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Function : unsigned char ReadRegByte(unsigned char reg)

Parameters : reg — Register to be read

Description : Read a byte from a register

Return : Value of register to be read

Notes : Refer to Datasheet for details of registers and parameters

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Function : void WriteRegBuf(unsigned char reg, unsigned char \*buf, char bytes)

Parameters : reg — Register to be written  
                  \*buf — Char Array to be written to a register  
                  bytes — Bytes of \*buf

Description : Write a char array to a register

Return : none

Notes : Refer to Datasheet for details of registers and parameters

---

Function : void ReadRegBuf(unsigned char reg, unsigned char \*buf, char bytes)

Parameters : reg — Register to be read  
                  \*buf — Char Array to be written from a register  
                  bytes — Bytes of \*buf

Description : Read a char array from a register to \*buf

Return : none

Notes : Refer to Datasheet for details of registers and parameters

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Function : void setMode(char mode)  
Parameters : mode — TX for transmitter  
                    RX for receiver  
Description : Switch the nRF24L01+ to Transmitter or Receiver Mode  
Return : none  
Notes : none

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Function : void Transmit(unsigned char \*pBuf, unsigned char plWidth)  
          void Transmit(char \*pBuf, unsigned char plWidth)  
Parameters : \*pBuf — Bytes to be sent out  
            plWidth — Number of bytes in pBuf will be sent  
Description : Transmit the data  
Return : none  
Notes : none

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Function : void WriteTXPayload(unsigned char \*pBuf, unsigned char plWidth)  
Parameters : \*pBuf — Bytes to be written to TX Payload Register  
            plWidth — Number of bytes in pBuf will be written  
Description : Write Payload to the TX Payload Width Ack. Register  
Return : none  
Notes : none

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Function : void setChannel(unsigned char RF\_Channel)  
Parameters : RF\_Channel — Set RF Channel which is from 0 to 125  
Description : Set the RF operating channel  
Return : none  
Notes : none

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Function : unsigned char getChannel(void)  
Parameters : none  
Description : Get the RF operating channel  
Return : RF operating Channel which is from 0 to 125  
Notes : none

Function : unsigned char getStatus(void)  
Parameters : none  
Description : Get the value of Status Register  
Return : The Value of Status Register  
Notes : Refer to Datasheet for details

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Function : unsigned char getRXPayloadWidth(unsigned char pipe)  
Parameters : pipe — Data Pipe which is from 0 to 5  
Description : Get the RX payload width of a Data Pipe  
Return : Payload Width of Data Pipe, which is from 1 to 32  
Notes : none

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Function : void setRXPayloadWidth(unsigned char pipe, unsigned char plWidth)  
Parameters : pipe — Data Pipe which is from 0 to 5  
plWidth — Set the Payload Width  
Description : Set the RX Payload width of a Data Pipe  
Return : none  
Notes : none

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Function : unsigned char getCurrentPipeNum(void)  
Parameters : none  
Description : Get the Current Pipe No., that Data is received  
Return : Data Pipe received data, which is from 0 to 5  
Notes : none

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Function : void getRXPlload(unsigned char \*pBuf)  
void getData(unsigned char \*pBuf)  
void getData(char \*pBuf)  
Parameters : \*pBuf — Get Received Data  
Description : Get Received Data  
Return : none  
Notes : none

Function : void getRXPlod(unsigned char \*pBuf, unsigned char \*pipe, unsigned char \*plWidth)  
 void getData(unsigned char \*pBuf, unsigned char \*pipe, unsigned char \*plWidth)  
 void getData(char \*pBuf, unsigned char \*pipe, unsigned char \*plWidth)

Parameters : \*pBuf — Get Received Data  
 \*pipe — Get Data Pipe, the data are came from which data pipe  
 \*plWidth — Get Payload Width

Description : Get Received Data

Return : none

Notes : none

Function : unsigned char getFIFO(void)

Parameters : none

Description : Get the value of FIFO register status

Return : the value of FIFO register status

Notes : Refer to Datasheet for details

Function : void setTXAddress(unsigned char \*pBuf, unsigned char addrWidth)

Parameters : \*pBuf — Char Array to be written to TX Address Register  
 addrWidth — Number of Bytes of \*pBuf to be written

Description : Set TX Address

Return : none

Notes : none

Function : void setRXAddress(unsigned char \*pBuf, unsigned char addrWidth, unsigned char pipe)  
 void setRXAddress(unsigned char pBuf, unsigned char addrWidth, unsigned char pipe)

Parameters : \*pBuf — Char Array to be written to RX Address Register  
 addrWidth — Number of Bytes of \*pBuf to be written  
 pBuf — Char to be written RX Address Register, Data pipe 2 to 5  
 pipe — Data Pipe to be set

Description : Set RX Address

Return : none

Notes : none

Function : void getTXAddress(unsigned char \*pBuf)  
Parameters : \*pBuf — Char Array to be written from a TX Address Register  
Description : Get TX Address  
Return : none  
Notes : none

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Function : void getRXAddress(unsigned char \*pBuf, unsigned char pipe)  
Parameters : \*pBuf — Char Array to be written from a RX Address Register  
pipe — Data Pipe to be select  
Description : Get RX Address  
Return : none  
Notes : none

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Function : void FlushTX(void);  
Parameters : none  
Description : Flush TX FIFO Buffer  
Return : none  
Notes : none

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Function : void FlushRX (void);  
Parameters : none  
Description : Flush RX FIFO Buffer  
Return : none  
Notes : none

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Function : void clearRxDr (void);  
Parameters : none  
Description : Clear Data Received Interrupt Flag  
Return : none  
Notes : none

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Function : void clearMaxRt (void);  
Parameters : none  
Description : Clear Max. Re-transmission Interrupt Flag  
Return : none  
Notes : none

Function : void clearStatusReg(void);  
Parameters : none  
Description : Clear Status Register  
Return : none  
Notes : none

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Function : unsigned char RxDR(void)  
          unsigned char Available(void)  
Parameters : none  
Description : Check whether Data is received  
Return : 1 for Data Received is ready.  
         0 for NO Data is received.  
Notes : none

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Function : unsigned char MaxRt (void)  
Parameters : none  
Description : Check whether Max. Retransmission Interrupt is occurred  
Return : 1 for Maximum number of TX retransmits interrupt.  
         0 for otherwise  
Notes : If 1 is returned, it is meant that the transmission  
         is failed. The data cannot be sent to target device.

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Function : unsigned char TxDs(void)  
          unsigned char isTransmitted(void)  
Parameters : none  
Description : Check whether Data is transmitted successfully.  
Return : 1 for Data is transmitted successfully.  
         0 for otherwise  
Notes : none

---

Function : unsigned char PacketLostCounter(void)  
Parameters : none  
Description : How many packets are lost during transmission.  
Return : How many packets are lost  
Notes : The maximum number of packet lost is 15.  
         Overflow will be occurred when it is greater than 15



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Function : void ClearPacketLostCounter(void)  
Parameters : none  
Description : Clear Packet Lost Counter Register  
Return : none  
Notes : none

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Function : unsigned char RetransmittedPackets(void)  
Parameters : none  
Description : Get how many Packets are retransmitted.  
Return : How Many Packets are retransmitted.  
Notes : none

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Function : bool isTxFIFOFull(void)  
Parameters : none  
Description : Check whether TX FIFO buffer is full.  
Return : true for TX FIFO Full  
false for Available locations in TX FIFO  
Notes : none

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Function : bool isTxFIFOEmpty (void)  
Parameters : none  
Description : Check whether TX FIFO buffer is empty.  
Return : true for TX FIFO is empty  
false for TX FIFO is not empty  
Notes : none

---

Function : bool isRxFIFOFull (void)  
Parameters : none  
Description : Check whether RX FIFO buffer is full.  
Return : true for RX FIFO Full  
false for Available locations in RX FIFO  
Notes : none

---

Function : bool isRxFIFOEmpty(void)  
Parameters : none  
Description : Check whether RX FIFO buffer is empty.  
Return : true for RX FIFO is empty  
          false for RX FIFO is not empty  
Notes : none

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Function : void EnableDynamicPayloadLength(void)  
Parameters : none  
Description : Enable Dynamic Payload Length Function. Let nRF24L01+ work in Dynamic Payload Mode.  
Return : none  
Notes : none

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Function : void DisableDynamicPayloadLength(void)  
Parameters : none  
Description : Disable Dynamic Payload Length Function.  
Return : none  
Notes : none

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Function : void DataPipeEnableDynamicPldLen(unsigned char pipe)  
Parameters : pipe — Data Pipe to be enable in Dynamic Payload Length  
Description : Set which Data Pipe is enabled in Dynamic Payload Length Mode  
Return : none  
Notes : none

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Function : void DataPipeDisableDynamicPldLen (unsigned char pipe)  
Parameters : pipe — Data Pipe to be disable in Dynamic Payload Length  
Description : Set which Data Pipe is disabled in Dynamic Payload Length Mode  
Return : none  
Notes : none

Function : bool isDynamicPDEnabled(void)  
Parameters : none  
Description : Set which Data Pipe is disabled in Dynamic Payload Length Mode  
Return : true for Enabled Dynamic Payload Length Mode  
false for not  
Notes : none